

Dubai Municipality Survey Section

Progress Towards a cm Geoid for Dubai Emirate

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H = Orthometric height
 h = Ellipsoidal height
 N = Geoid undulation

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Definition of the Geoid

Geoid is the equipotential surface of the gravity field of the earth.

Geoid : Level surface of global undisturbed oceans

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Earth Surfaces

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Geoid – Ellipsoid Separation

$$N = \frac{R}{4\pi G} \iint \Delta g S(\psi) d\sigma$$

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GPS Heighting

$H = h - N$

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Spirit levelling Vs GPS

- Traditional means for establishing vertical control (H): spirit-levelling
 - costly
 - labourious
 - inefficient, difficult in remote areas, mountainous terrain, over large regions
- With advent of satellite-based global positioning systems (GPS) 3D positioning has been revolutionized

$h - H - N = 0$

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Why to combine h , H and N ??

- modernize regional vertical datums
- unify/connect national regional datums between neighbouring countries
- transform between different types of height data (GPS-levelling)
- refine and test existing gravimetric geoid models
- better understanding of data error sources
 - calibrate geoid error model
 - assess noise in GPS heights, test a-priori error measures
 - evaluate levelling precision, test a-priori error values
- Other applications: sea level change monitoring, post-glacial rebound studies, etc.

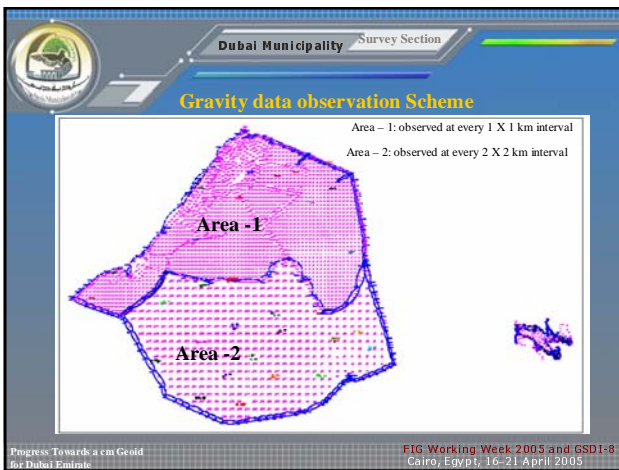
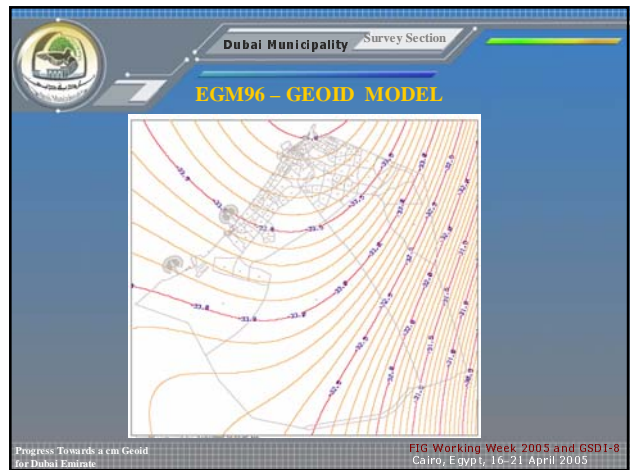
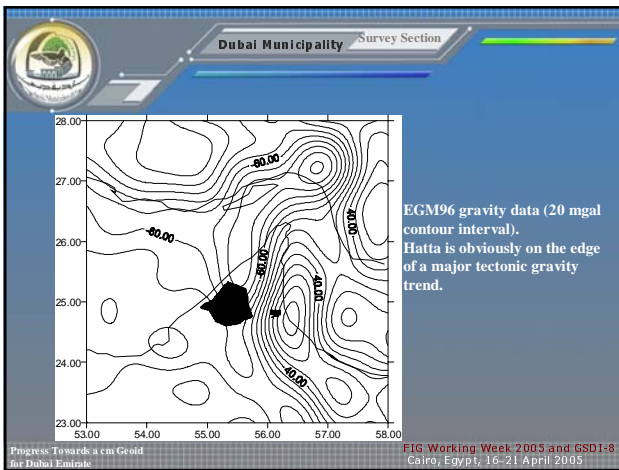
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Problems of combining heterogeneous heights

- random errors in the derived heights h , H , and N
- datum inconsistencies inherent among the height types
- systematic effects and distortions (long-wavelength geoid errors, poorly modelled GPS errors and over-constrained levelling network adjustments)
- assumptions/theoretical approximations made in processing observed data (neglecting sea surface topography or river discharge corrections at tide gauges)
- approximate or inexact normal/orthometric height corrections
- instability of reference station monuments over time (geodynamic effects, land uplift/subsidence)

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Statistics of Gravity Data Reduction

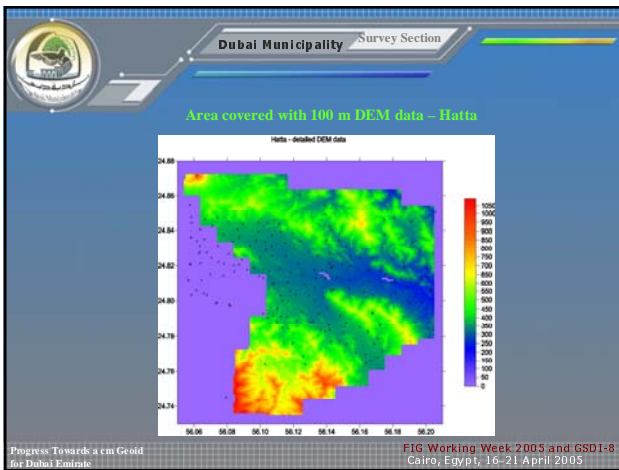
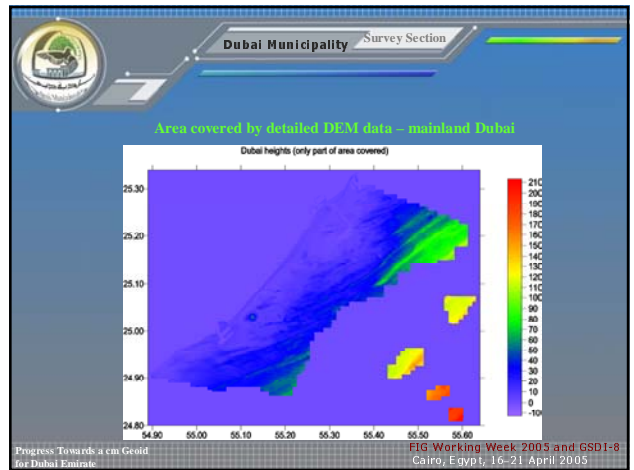
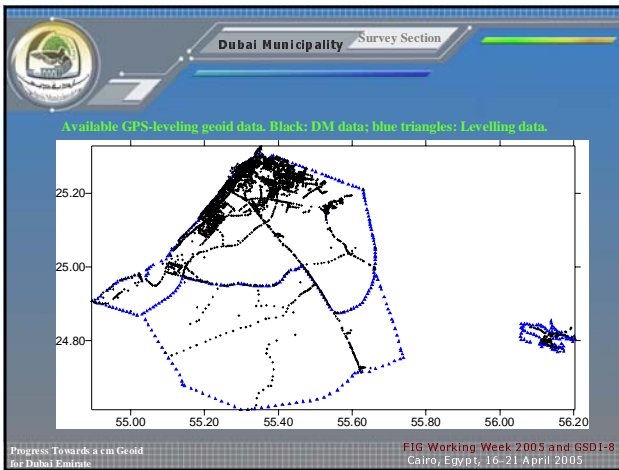
Statistics of gravity data reductions

All data (9206 pts)	Mean	Std. dev	Min	Max
Unit: mgal				
Original data	-54	40.1	-128	132
- EGM	-5	13	-78.8	62.3
- EGM - RTM (60°)	-2.7	12.3	-70.6	66.9
- EGM - RTM (30°)	-3.9	12.4	-78.4	69.9
- EGM - Isostatic	-0.6	13.5	-69.1	66.7

Dubai main area gravimetry (2881 pts)	Mean	Std. dev	Min	Max
Unit: mgal				
Original data	-72	10.9	-95.6	51
- EGM	-8.8	11.2	-40.5	8.3
- EGM - RTM (60°)	-6.5	11.3	-44.4	10.9
- EGM - RTM (30°)	-8.2	10.9	-32.6	9.1
- EGM - Isostatic	-5.6	11.2	-52.5	13.7

Hatta gravimetry only (199 pts)	Mean	Std. dev	Min	Max
Unit: mgal				
Original data	66.5	19	44.7	132
- EGM	-18	18.1	-42.7	62.3
- EGM - RTM (60°)	-22	16.3	-45.4	32.7
- EGM - RTM (30°)	-11	15.8	-33.9	40.1
- EGM - Isostatic	-31	16.1	-54.4	22.6

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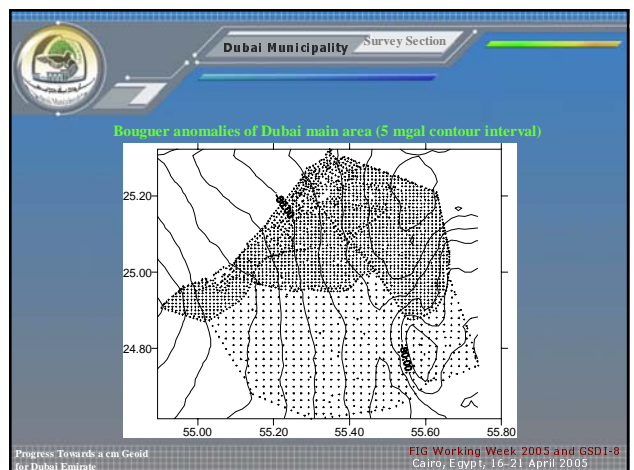
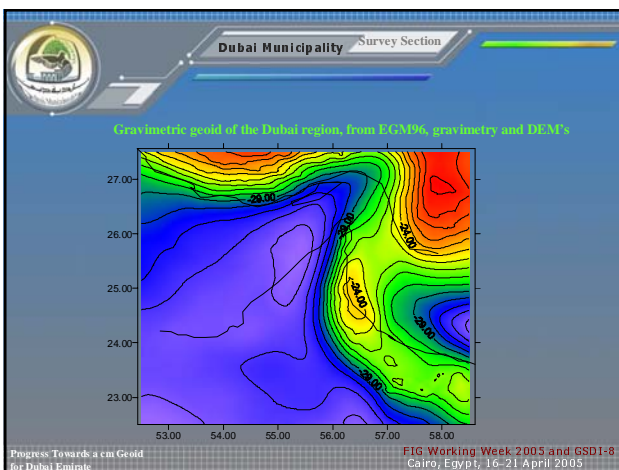


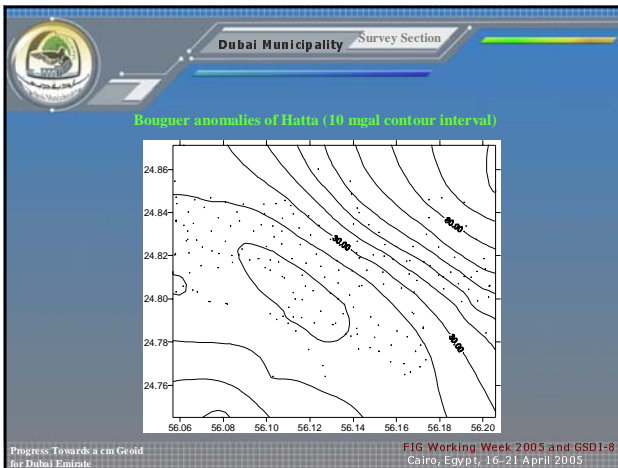
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Comparisons of gravimetric geoid to Dubai Municipality GPS leveling

Unit: m	Mean	Std.dev.
Dubai area (3157 GPS pts) Gravimetric geoid	-1.40	0.09
EGM96 only	-0.83	0.16
Hatta area (110 pts) Gravimetric geoid	-1.39	0.12
EGM96	-1.52	0.25

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The gravimetric geoid computation

The Dubai precise geoid has been computed in two steps

- A gravimetric geoid model, computed by spherical FFT in a global datum
- A GPS-tailored local geoid, which fits the GPS observations and the Dubai vertical datum to a few cm. This step has involved an iterative editing of GPS-leveling outliers.

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- ### Why to use FFT ?
- FFT provides very fast evaluation of convolution sums/integrals with gridded data
 - In planar approximation, the Stokes and terrain correction integrals are convolutions
 - In spherical approximation, these integrals are convolutions along the parallels, and so are the summations for the GM-contributions
 - Gravity and topography data are usually provided on regular grids
 - Computations for very large areas can be performed on a PC
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- ### Geoid undulations by FFT
- Computational Procedure :
- Subtract effect of GM from Δg (long wavelength)
 - Subtract effect of terrain from Δg (short wavelength)
 - Use the reduced Δg in the FFT formulas
 - Add to the results (reduced co-geoid) the GM effect
 - Add to the results (reduced co-geoid) the indirect terrain effects
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Gravimetric Geoid Computation

The Geoid signal N is constructed by subdividing it into three parts

$$N = N_1 + N_2 + N_3$$

Where

- N_1 = Spherical harmonic expansion complete to degree and order 360
- N_2 = From the topography
- N_3 = From contributions of residual gravity

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Long wave length Geoid contribution

$$\Delta g_p^{GM} = G \sum_{n=2}^{n_{max}} (n-1) \sum_{m=0}^n [C_{nm} \cos m\lambda_p + S_{nm} \sin m\lambda_p] P_{nm}(\sin \varphi_p)$$

$$N_p^{GM} = R \sum_{n=2}^{n_{max}} \sum_{m=0}^n [C_{nm} \cos m\lambda_p + S_{nm} \sin m\lambda_p] P_{nm}(\sin \varphi_p)$$

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Medium wave length Geoid contribution

$$N(x_k, y_l) = \frac{1}{2\pi\gamma} \{F_l \Delta g(x_k, y_l) + F_l \bar{N}(x_k, y_l)\} = \frac{1}{2\pi\gamma} \{F_l \Delta \bar{G}(u_m, v_n) + \bar{N}(u_m, v_n)\}$$

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Short wave length Geoid contribution

$$\delta N_p \approx -\frac{\pi k \rho}{\gamma} H_p^2 - \frac{k \rho}{6\gamma} \iint_E \frac{H^3 - H_p^3}{l^3} dx dy$$

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Fitting the geoid to GPS/levelling data

$$\epsilon = N_{\text{grav}} - N_{\text{GPS}} = f(\varphi, \lambda) + \epsilon'$$

The basic principle used here is to model the gravimetric and GPS geoid difference by a smooth function consisting of a trend function f (a polynomial) and a residual ϵ' , to be modeled by least/squares collocation

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Problem Formulation

Standard practice: Use of a corrector surface to model the datum discrepancies and systematic effects when combining GPS, geoid and orthometric heights

Theory: $h_i - H_i - N_i = 0 \rightarrow N_i^{\text{GPS/levelling}} = N_i$

Practice: $h_i - H_i - N_i = l_i \rightarrow N_i^{\text{GPS/levelling}} \neq N_i$

Model: $l_i = h_i - H_i - N_i = \mathbf{a}_i^T \mathbf{x} + v_i$

↑ residuals
parametric model

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Improving the GPS Heighting

$$H_A = h_A - N_A \quad \text{or} \quad h_A - H_A - N_A = 0 \quad \text{Eqn-1}$$

Where, H_A = orthometric height, h_A = ellipsoidal height, N_A = Geoidal Separation

$$h_i - H_i - N_i = c_i^T x + v_i \quad \text{Eqn-2}$$

$$c_i^T x = \cos \varphi_i \cos \lambda_i x_1 + \cos \varphi_i \sin \lambda_i x_2 + \sin \varphi_i x_3 + x_4 \quad \text{Eqn-3}$$

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Semi-automated Parametric Model Testing Procedure

■ To eliminate some of the arbitrariness in both choosing the model type and assessing its performance

■ Developed a procedure consisting of five major modules

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R.M.S. fit of GPS leveling data to the geoid

Unit: m	Mean	Std. dev.	Min	Max
All data (3540 pts.)	-0	0.041	-0.269	0.245
DM GPS data, Dubai main (3212 pts)	0	0.036	-0.215	0.198
Hansa GPS data, Dubai (150 pts)	0	0.05	-0.115	0.21
Hatta area (110 pts.)	-0.01	0.11	-0.423	0.461

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Testing the Geoid Model

GEOID QC 35 STATIONS NETWORK

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MAIN-LAND

Accuracy tested for stations from main data base

method of observation	Accuracy within 5 cm	%	Accuracy more than 5 cm	%	total station
fast static, kinematic	2857	87	440	13	3297
static method (more than 1 h)	318	87	49	13	367

Accuracy tested from the network which observed to test the GM

		%
Total Number of Stations observed	35	
Stations with +/- 2cm	25	71
Stations with +/- 3cm	4	11
Stations with +/- 4cm	4	12
Stations with +/- 5cm more	1	3
Outlier	1	3

Note : 100% Station are within 5 cm

HATTA

method of observation	Accuracy within 10 cm	%	Accuracy more than 10 cm	%	total station
static, fast static, kinematic	99	85	16	14	115

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Dubai geoid computed from gravity, GPS and leveling Contour interval 20 cm.

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Dubai Geoid from gravity, GPS and Levelling

Dubai geoid from gravity, GPS and levelling

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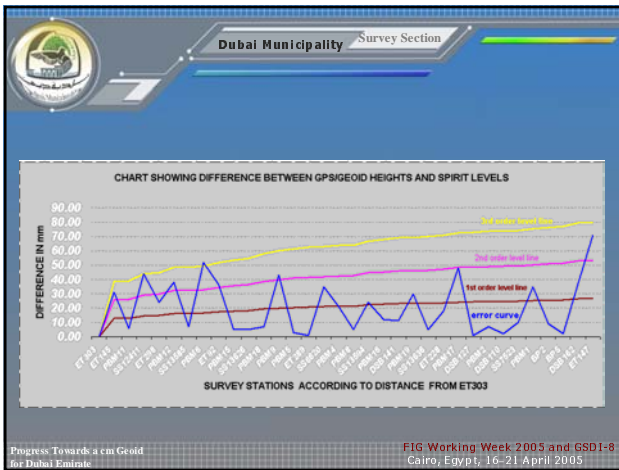
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DM-GEOID MODEL

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Precise Dubai Geoid Model - Program

Precise Dubai Geoid Model (PEGM)

Input Method: Single Point

Coordinate System on WGS84: DLTM, UTM, Geographic, Cartesian

Input-DTM Coordinates: Northing: 2779607.836, Easting: 489075.422, Ellipsoid Ht: 28.262

Output: Undulation: 34.76, Orthometric Ht: 6.50

Developed by Survey Section, DM

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CONCLUSION

- The derived Geoid model is precise enough to meet the Third order levelling Standards.
- In the main land Dubai the accuracy could be of the order of 1-3 cm on average
- In Hatta region the accuracy could be of 5-10 cm. Still more information and data is necessary to improve the model in this region.
- We believe this Geoid model could meet the requirement of many potential users who would intend to convert GPS heights into their corresponding Mean Sea Level heights.

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